

四 角運動量の合成 (スピン - 軌道力)

。 複習

$$[l_i, l_j] = i \epsilon_{ijk} l_k$$

$$[l_x, l_y] = i l_z$$

$$[l_y, l_z] = i l_x$$

$$[l_z, l_x] = i l_y$$

$$l_{\pm} \equiv l_x \pm i l_y$$

$$l_{\pm} |l m\rangle = \sqrt{(l \mp m)(l \pm m + 1)} |l m \pm 1\rangle$$

。 l-s 力

$$\vec{J} = \vec{L} + \vec{S}$$

$$\begin{aligned} \text{(note)} \quad \vec{J}^2 &= \vec{L}^2 + \vec{S}^2 + 2\vec{L} \cdot \vec{S} \\ &= \vec{L}^2 + \vec{S}^2 + 2L_z S_z + L_+ S_- + L_- S_+ \end{aligned}$$

角度成分とスピン部分の積 : $Y_{lm} X_{ms}$

$$m_j = m_l + m_s$$

$$l + \frac{1}{2}$$

$$Y_{ll} X_{\uparrow}$$

$$l - \frac{1}{2}$$

$$Y_{l, l-1} X_{\uparrow}$$

$$Y_{ll} X_{\downarrow}$$

$$l - \frac{3}{2}$$

$$Y_{l, l-2} X_{\uparrow}$$

$$Y_{l, l-1} X_{\downarrow}$$

⋮

$$-l - \frac{1}{2}$$

$$Y_{l, l-1} X_{\downarrow}$$

$$\begin{aligned}
 \vec{J}^2 Y_{\ell\ell} \chi_{\uparrow} &= (\vec{L}^2 + \vec{S}^2 + 2L_z S_z + \cancel{L_+ S_-} + \cancel{L_- S_+}) Y_{\ell\ell} \chi_{\uparrow} \\
 &= \left[\ell(\ell+1) + \frac{3}{4} + \ell \right] Y_{\ell\ell} \chi_{\uparrow} \\
 &\quad \parallel \\
 &\quad \ell^2 + 2\ell + \frac{3}{4} = \left(\ell + \frac{1}{2}\right) \left(\ell + \frac{3}{2}\right)
 \end{aligned}$$

$$\Downarrow Y_{\ell\ell} \chi_{\uparrow} = \left| \ell + \frac{1}{2}, \ell + \frac{1}{2} \right\rangle$$

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$$\begin{aligned}
 (L_- + S_-) Y_{\ell\ell} \chi_{\uparrow} &= \frac{\hbar - \left| \ell + \frac{1}{2}, \ell + \frac{1}{2} \right\rangle}{\sqrt{\left(\ell + \frac{1}{2} + \ell + \frac{1}{2}\right) \left(\ell + \frac{1}{2} - \ell - \frac{1}{2} + 1\right)}} \\
 &\quad \times \left| \ell + \frac{1}{2}, \ell - \frac{1}{2} \right\rangle \\
 &= \sqrt{2\ell + 1} \left| \ell + \frac{1}{2}, \ell - \frac{1}{2} \right\rangle \\
 &\rightarrow = \sqrt{2\ell} Y_{\ell\ell-1} \chi_{\uparrow} + Y_{\ell\ell} \chi_{\downarrow}
 \end{aligned}$$

$$\Downarrow \left| \ell + \frac{1}{2}, \ell - \frac{1}{2} \right\rangle = \sqrt{\frac{2\ell}{2\ell+1}} Y_{\ell\ell-1} \chi_{\uparrow} + \frac{1}{\sqrt{2\ell+1}} Y_{\ell\ell} \chi_{\downarrow}$$

これと直交する状態を作ってみると:

$$\frac{1}{\sqrt{2\ell+1}} Y_{\ell\ell-1} \chi_{\uparrow} - \sqrt{\frac{2\ell}{2\ell+1}} Y_{\ell\ell} \chi_{\downarrow}$$

$$\text{(note)} \quad \vec{J}^2 (Y_{\ell\ell-1} \chi_{\uparrow} - \sqrt{2\ell} Y_{\ell\ell} \chi_{\downarrow})$$

$$= (\vec{L}^2 + \vec{S}^2 + 2L_z S_z + L_+ S_- + L_- S_+) (Y_{\ell\ell-1} \chi_{\uparrow} - \sqrt{2\ell} Y_{\ell\ell} \chi_{\downarrow})$$

$$= \left(l(l+1) + \frac{3}{4} + 2(l-1) \cdot \frac{1}{2} \right) + \sqrt{(l-l+1)(l+l-1+1)} \sqrt{\left(\frac{1}{2} + \frac{1}{2}\right)\left(\frac{1}{2} - \frac{1}{2} + 1\right)}$$

$$\times Y_{l-1} X_{\uparrow} \quad \times Y_{ll} X_{\downarrow}$$

$$- \sqrt{2l} \left(l(l+1) + \frac{3}{4} + 2l \cdot \left(-\frac{1}{2}\right) \right) Y_{ll} X_{\downarrow} - \sqrt{2l} \sqrt{2l} Y_{l-1} X_{\uparrow}$$

$$= \left(l^2 + l + \frac{3}{4} + l - 1 - 2l \right) Y_{l-1} X_{\uparrow}$$

$$- \sqrt{2l} \left(l^2 + l - l + \frac{3}{4} - 1 \right) Y_{ll} X_{\downarrow}$$

$$= \left(l^2 - \frac{1}{4} \right) \left(Y_{l-1} X_{\uparrow} - \sqrt{2l} Y_{ll} X_{\downarrow} \right)$$

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$$|l - \frac{1}{2}, l - \frac{1}{2}\rangle = \frac{1}{\sqrt{2l+1}} Y_{l-1} X_{\uparrow} - \frac{\sqrt{2l}}{\sqrt{2l+1}} Y_{ll} X_{\downarrow}$$

まとめ

$j_2 = l - \frac{1}{2}$ を持つ状態

$$Y_{ll} \chi_{\downarrow} \quad \text{と} \quad Y_{l, l-1} \chi_{\uparrow}$$

適当な線形結合をとることによって

$$\begin{cases} |l + \frac{1}{2}, l - \frac{1}{2}\rangle = \sqrt{\frac{2l}{2l+1}} Y_{l, l-1} \chi_{\uparrow} + \sqrt{\frac{1}{2l+1}} Y_{ll} \chi_{\downarrow} \\ |l - \frac{1}{2}, l - \frac{1}{2}\rangle = \sqrt{\frac{1}{2l+1}} Y_{l, l-1} \chi_{\uparrow} - \sqrt{\frac{2l}{2l+1}} Y_{ll} \chi_{\downarrow} \end{cases}$$

一般に

$$|l + \frac{1}{2}, m\rangle = \alpha Y_{l, m - \frac{1}{2}} \chi_{\uparrow} + \beta Y_{l, m + \frac{1}{2}} \chi_{\downarrow}$$

$$|l - \frac{1}{2}, m\rangle = \beta \quad \quad \quad - \alpha \quad \quad \quad$$

或いは

$$|j, m\rangle = \sum_{m_l, m_s} \underbrace{\langle l, m_l, \frac{1}{2}, m_s | j, m \rangle}_{\text{クレープシュ・コルダニ係数}} Y_{l, m_l} \chi_{m_s}$$

クレープシュ・コルダニ係数

$$\vec{J} = \vec{L}^2 + \vec{S}^2 + 2\vec{L} \cdot \vec{S}$$

$$\Downarrow \vec{L} \cdot \vec{S} = \frac{1}{2} (\vec{J}^2 - \vec{L}^2 - \vec{S}^2)$$

$$\Downarrow \vec{L} \cdot \vec{S} |j m\rangle = \frac{1}{2} \left[j(j+1) - l(l+1) - \frac{3}{4} \right] |j m\rangle$$

$$j = l + \frac{1}{2} :$$

$$\frac{1}{2} \left[\left(l + \frac{1}{2}\right) \left(l + \frac{3}{2}\right) - l(l+1) - \frac{3}{4} \right]$$

$$= \frac{1}{2} \left(\cancel{l^2} + 2l + \frac{3}{4} - \cancel{l^2} - l - \frac{3}{4} \right) = \frac{1}{2} l$$

$$j = l - \frac{1}{2} :$$

$$\frac{1}{2} \left[\left(l - \frac{1}{2}\right) \left(l + \frac{1}{2}\right) - l(l+1) - \frac{3}{4} \right]$$

$$= \frac{1}{2} \left(\cancel{l^2} - \frac{1}{4} - \cancel{l^2} - l - \frac{3}{4} \right) = -\frac{1}{2} (l+1)$$