## 6.2. スピッと軌道角運動量。合成

## 例) 水素原子

状態 a 分類:

 $m = \ell + \frac{1}{2} :$ 

 $M = \ell - \frac{1}{2}$ :

 $m = \ell - \frac{3}{2} :$ 

17ee > 17) 17ee > 17) 17ee > 14 > 17ee-2 > 17 > , | Yee-1 > 14 >

 $M = -l + \frac{1}{2}$ :

 $\mathcal{M} = -l - \frac{1}{2} :$ 

計 (20+1) x 2 = 9 拟影

$$\rightarrow$$
  $j = l + \frac{1}{2}$ ,  $-l - \frac{1}{2} \leq m \leq l + \frac{1}{2}$  (2l+2  $\geq$  )  $\geq j = l - \frac{1}{2}$ ,  $-l + \frac{1}{2} \leq m \leq l - \frac{1}{2}$  (2l  $\geq$  )  $q \neq \chi$  終 に分類 しなよす。

(j², j2, 0°, 5°) の同時固有状態をつてる。

o (note) 
$$\chi c^{\circ} >$$
 軌道 $h : V = \chi \vec{l} \cdot \vec{J}$   
 $j^{2} = \ell^{2} + g^{2} + 2\ell \cdot g \rightarrow V = \frac{d}{2} (j^{2} - \ell^{2} - g^{2})$   
 $j^{2} = \ell^{2} \ell g^{2} + g^{2} \ell g = g \ell g = g \ell g$ 

$$\int_{-\frac{\pi}{2}}^{2} \left| \left\langle \left( \frac{1}{2} + 1 \right) + \frac{\pi}{2} \left( \frac{1}{2} + 1 \right) + \frac{2\ell \cdot \frac{\pi}{2}}{2} \right\rangle \right| \left\langle \left( \frac{\pi}{2} + 2\ell + \frac{3}{4} \right) \right| \left\langle \left( \frac{\pi}{2} + 2\ell + \frac{3}{4} \right) \right\rangle \right\rangle \\
= \int_{-\frac{\pi}{2}}^{2} \left( \ell^{2} + 2\ell + \frac{3}{4} \right) \left| \left( \frac{\pi}{2} + 2\ell \right) \right\rangle \\
= \int_{-\frac{\pi}{2}}^{2} \left( \ell^{2} + 2\ell + \frac{3}{4} \right) \left| \left( \frac{\pi}{2} + 2\ell \right) \right\rangle \\
= \int_{-\frac{\pi}{2}}^{2} \left( \ell^{2} + 2\ell + \frac{3}{4} \right) \left| \left( \frac{\pi}{2} + 2\ell \right) \right\rangle \\
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= \int_{-\frac{\pi}{2}}^{2} \left( \ell^{2} + 2\ell + 2\ell \right) \left| \left( \frac{\pi}{2} + 2\ell \right) \right| \\
= \int_{-\frac{\pi}{2}}^{2} \left( \ell^{2} + 2\ell + 2\ell \right) \left| \left( \frac{\pi}{$$

| j=l±½, me+½) = d± [Yeme > 11 > + β± |Yeme+1 > 11>

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$$\ell_{-} | Y_{14} \rangle = \sqrt{2} | Y_{10} \rangle$$
  
 $\ell_{-} | Y_{10} \rangle = \sqrt{2} | Y_{1-1} \rangle$ 

## 6.3. 一般。場合

$$\mathcal{J} = \dot{\mathcal{J}_1} + \dot{\mathcal{J}_2}$$

- ①  $|J=\hat{J}_1+\hat{J}_2|$ ,  $M=\hat{J}_1+\hat{J}_2>=|\hat{J}_1\hat{J}_1>|\hat{J}_2\hat{J}_2>$ (これは一通ソレかない)
- (2)  $|J=j_1+j_2|, M=j_1+j_2-1> \ll J-|j_1+j_2|, j_1+j_2>$
- U ③ là,+à2, à,+à2-1>に直交する状態を作ると、それは là,+à2-1, à,+à2-1>
  - - ⑤ これら 2フの状態に直をする状態は 111+12-2, 1,+12-2>

 $|JM\rangle = Z_{m_1,m_2} \langle j, m, j_2 m_2 | JM \rangle | j, m, \rangle | j_3 m_2 \rangle$ 

展開係数(クレブシュ・コールダン係数)

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(note) 
$$J = J_1 + J_2$$
  

$$J^2 = J_1^2 + J_2^2 + 2J_{12}J_{22} + (J_{1x} + iJ_{1y})(J_{2x} - iJ_{2y}) + (J_{1x} - iJ_{1y})(J_{2x} + iJ_{2y})$$

$$\mathcal{J}^{2} | \hat{J}_{1} \hat{J}_{1} \rangle | \hat{J}_{2} \hat{J}_{2} \rangle 
= \hat{h}^{2} \left( \hat{J}_{1} (\hat{J}_{1}+1) + \hat{J}_{2} (\hat{J}_{2}+1) + 2\hat{J}_{1} \hat{J}_{2} \right) | \hat{J}_{1} \hat{J}_{1} \rangle | \hat{J}_{2} \hat{J}_{2} \rangle 
\hat{J}_{1}^{2} + 2\hat{J}_{1} \hat{J}_{2} + \hat{J}_{2}^{2} + \hat{J}_{1} + \hat{J}_{2} 
(\hat{J}_{1} + \hat{J}_{2})^{2} + \hat{J}_{1} + \hat{J}_{2} 
(\hat{J}_{1} + \hat{J}_{2}) (\hat{J}_{1} + \hat{J}_{2} + 1)$$

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1, + 1/2- 2		
1,+12-1	B 1 前: 1 - 1 > 1 1 注注 >	
$\overline{U} = \underline{J}_1 + \underline{J}_2$ $\overline{J}_2 = \underline{J}_1 + \underline{J}_2$	3i+3z   $3i3i> 3i3i>$   $3x = 3x + 3z - 3i + 3z - 3i$	$-\hat{\mathbf{J}}_1 - \hat{\mathbf{J}}_2$

Sergai Japan

[15]) 
$$l_1 = 1 \times l_2 = 1 g 后成: L = l_1 + l_2$$

. 
$$L = |20\rangle \propto |Y_{1-1}\rangle |Y_{10}\rangle + 2|Y_{1-1}\rangle |Y_{10}\rangle + 2|Y_{10}\rangle |Y_{1-1}\rangle + |Y_{10}\rangle |Y_{1-1}\rangle$$

$$|00\rangle = \langle |Y_{1-1}\rangle |Y_{11}\rangle + \beta |Y_{10}\rangle |Y_{10}\rangle + \delta |Y_{11}\rangle |Y_{1-1}\rangle$$

$$\langle 20|00\rangle = 0 \rightarrow \forall + 2\beta + 8 = 0$$

$$\langle 10|00\rangle = 0 \rightarrow \forall - 8 = 0$$

$$\forall \forall = 8$$

$$|100\rangle = \frac{1}{\sqrt{3}} \left( |Y_{1-1}\rangle |Y_{11}\rangle - |Y_{10}\rangle |Y_{10}\rangle + |Y_{11}\rangle |Y_{1-1}\rangle \right)$$